

# What's so interesting about models with recurrent depth?

Jonas Geiping



**MAX PLANCK INSTITUTE**  
FOR INTELLIGENT SYSTEMS



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## Scaling up Test-Time Compute with Latent Reasoning: A Recurrent Depth Approach

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Bhavya Kailkhura<sup>3</sup> Abhinav Bhatele<sup>2</sup> Tom Goldstein<sup>2</sup>

Paper:

<https://www.arxiv.org/abs/2502.05171>

Code:

[github.com/seal-rg/recurrentpretraining](https://github.com/seal-rg/recurrentpretraining)

Model:

[huggingface.co/tomg-group-umd/huginn-0125](https://huggingface.co/tomg-group-umd/huginn-0125)

Data (still uploading):

[huggingface.co/datasets/tomg-group-umd/huginn-dataset](https://huggingface.co/datasets/tomg-group-umd/huginn-dataset)



# Key Concepts



# What is Test-Time Compute?

Improving the performance of a machine learning model by using more computation at test-time/ for inference.

# What is "Reasoning"

Learning to pattern match abstract concepts such as meta-strategies, logic, abstraction and plans, instead of just memorizing facts.

# What is *Verbalized Reasoning*

Strategized optimal cargo placement across aircraft zones.

🕒 2m, 9s

To solve this problem, I need to find a valid arrangement of the five cargo items (A, B, C, D, E) across the three zones (Front, Middle, Rear) that satisfies all of the given constraints.

Let me first summarize the constraints and items:

## **Aircraft Zones:**

- Front: max 2000kg, 8m<sup>3</sup>
- Middle: max 3000kg, 12m<sup>3</sup>
- Rear: max 2500kg, 10m<sup>3</sup>

## **Cargo Items:**

- Item A: 1200kg, 5m<sup>3</sup>, hazard class H1, priority 2, CG impact +5 per 100kg
- Item B: 800kg, 4m<sup>3</sup>, hazard class H2, priority 1, CG impact -3 per 100kg
- Item C: 1500kg, 6m<sup>3</sup>, hazard class H1, priority 3, CG impact +2 per 100kg

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This arrangement doesn't work. Let's try another.

Attempt 2:

- B and E in the Rear (priority 1)
- A and D in the Front (ensuring H1 and H3 aren't adjacent)
- C in the Middle

Let's check:

**Front:** Items A + D (1200kg + 1800kg = 3000kg, 5m<sup>3</sup> + 7m<sup>3</sup> = 12m<sup>3</sup>) - exceeds weight limit (3000kg > 2000kg)

This doesn't work either. Let's try another arrangement.

Attempt 3:

- B and E in the Rear (priority 1)
- A in the Front

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Strategized optimal cargo placement across aircraft zones.

🕒 2m, 9s

This gives us these potential arrangements when B + A are in the Rear:

1. Front: E, Middle: C+D (C is H1, D is H3 - invalid)
2. Front: C, Middle: E+D (C is H1, D is H3 - invalid)
3. Front: D, Middle: E+C (A is H1 in Rear, D is H3 in Front, C is H1 in Middle - both A and C are not adjacent to D, so this is valid!)
4. Front: E+C, Middle: D (C is H1, D is H3 - invalid)

7m<sup>3</sup> = 12m<sup>3</sup> - exceeds weight limit (3000kg >

nt.

So, we have a valid arrangement!

- Front: D (1800kg, 7m<sup>3</sup>, H3)
- Middle: E (900kg, 3m<sup>3</sup>, H2, P1) + C (1500kg, 6m<sup>3</sup>, H1) = 2400kg, 9m<sup>3</sup>
- Rear: B (800kg, 4m<sup>3</sup>, H2, P1) + A (1200kg, 5m<sup>3</sup>, H1) = 2000kg, 9m<sup>3</sup>

This satisfies:

- Weight and volume constraints for all zones



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Strategized optimal cargo placement across aircraft zones.

This gives us these potential arrangements when B + A are in the Front zone:

1. Front: E, Middle: C+D (C is H1, D is H3 - invalid)
2. Front: C, Middle: E+D (C is H1, D is H3 - invalid)
3. Front: D, Middle: E+C (A is H1 in Rear, D is H3 in Front, adjacent to D, so this is valid!)
4. Front: E+C, Middle: D (C is H1, D is H3 - invalid)

So, we have a valid arrangement!

- Front: D (1800kg, 7m<sup>3</sup>, H3)
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2m, 9s

second (from the Middle). So in terms of priority item accessibility, all three arrangements are equally optimal.

Since all three arrangements satisfy all constraints and have the same CG impact, and are equally optimal in terms of priority item accessibility, any of them could be considered the "optimal" arrangement. For the sake of providing a specific answer, I'll go with Arrangement 3:

- Front: D (1800kg, 7m<sup>3</sup>, H3)
- Middle: B (800kg, 4m<sup>3</sup>, H2, P1) + A (1200kg, 5m<sup>3</sup>, H1)
- Rear: E (900kg, 3m<sup>3</sup>, H2, P1) + C (1500kg, 6m<sup>3</sup>, H1)

So the optimal arrangement of the five cargo items across the three zones is:

- Front Zone: Item D
- Middle Zone: Items B and A
- Rear Zone: Items E and C

To solve the Automated Aircraft Loading Problem, I need to find an arrangement that satisfies all constraints while optimizing for priority access.

Here's the optimal solution:

## Front Zone:

- Item D (1800kg, 7m<sup>3</sup>, hazard class H3)

## Middle Zone:

- Item B (800kg, 4m<sup>3</sup>, hazard class H2, priority 1)
- Item A (1200kg, 5m<sup>3</sup>, hazard class H1)

## Rear Zone:

- Item E (900kg, 3m<sup>3</sup>, hazard class H2, priority 1)
- Item C (1500kg, 6m<sup>3</sup>, hazard class H1)

This solution satisfies all constraints:

# *Continuous Reasoning?*

Moving the reasoning chain into the model's representation space.

# A Recurrent-Depth Approach



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**Hopfield-Amari Models?**

Equilibrium Models

Representation Recycling

Diffusion Models

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# Why use recurrent-depth as a framework for test-time compute?

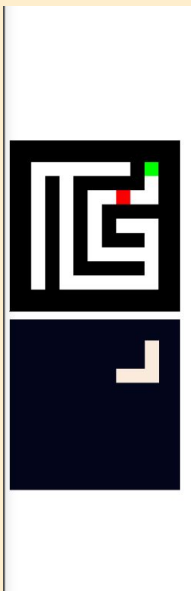
- No supervision on intermediate steps, so no CoT data needed with the right training objective
- No increased context length, linear complexity increase
- Recurrent-depth models have less parameters
  
- Recurrent-depth models are *compute-heavy*

# A good prior for "Reasoning"?

- Easy to learn iterative *algorithms*
- Harder for the model to memorize

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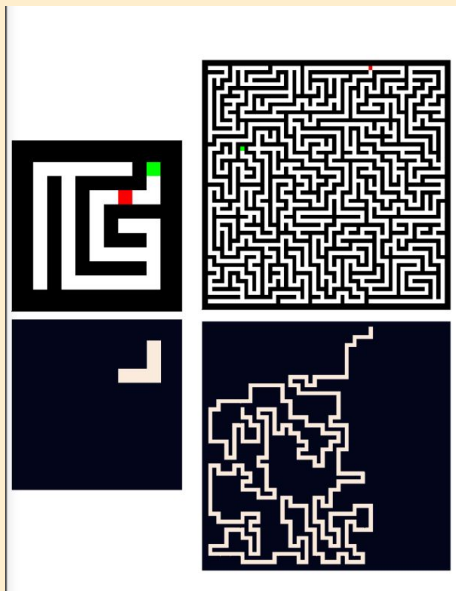
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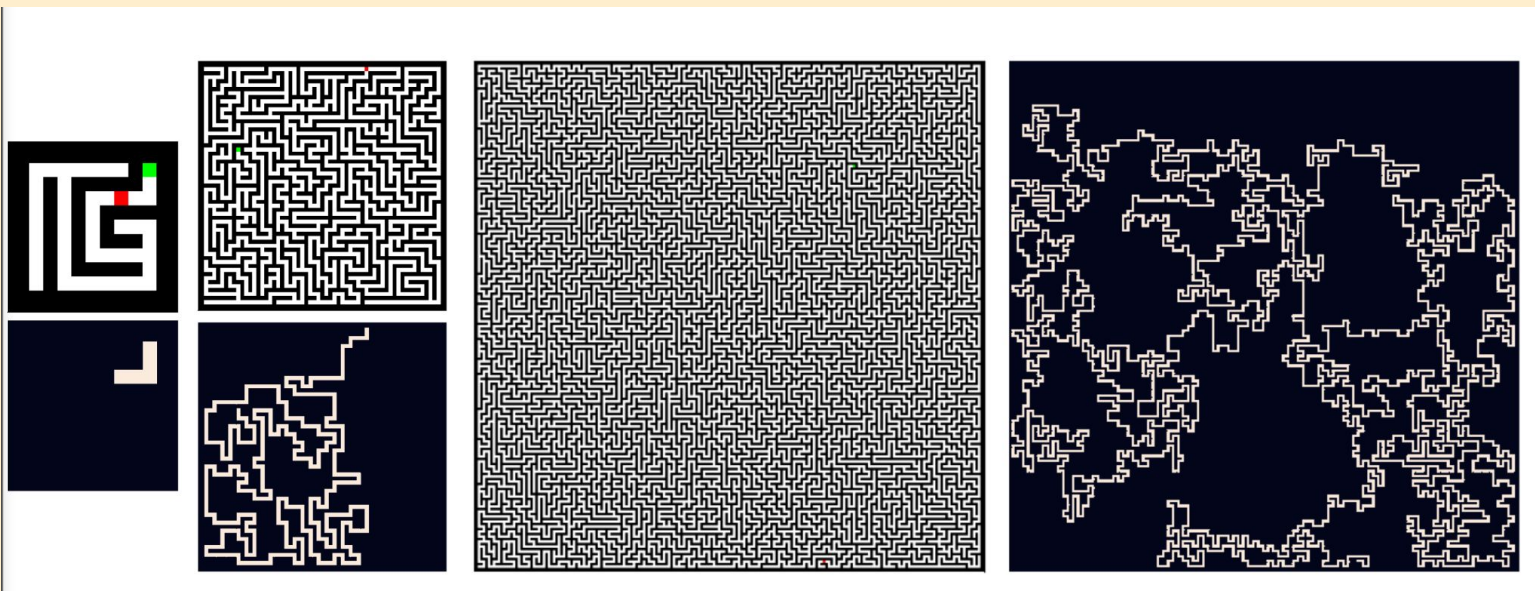
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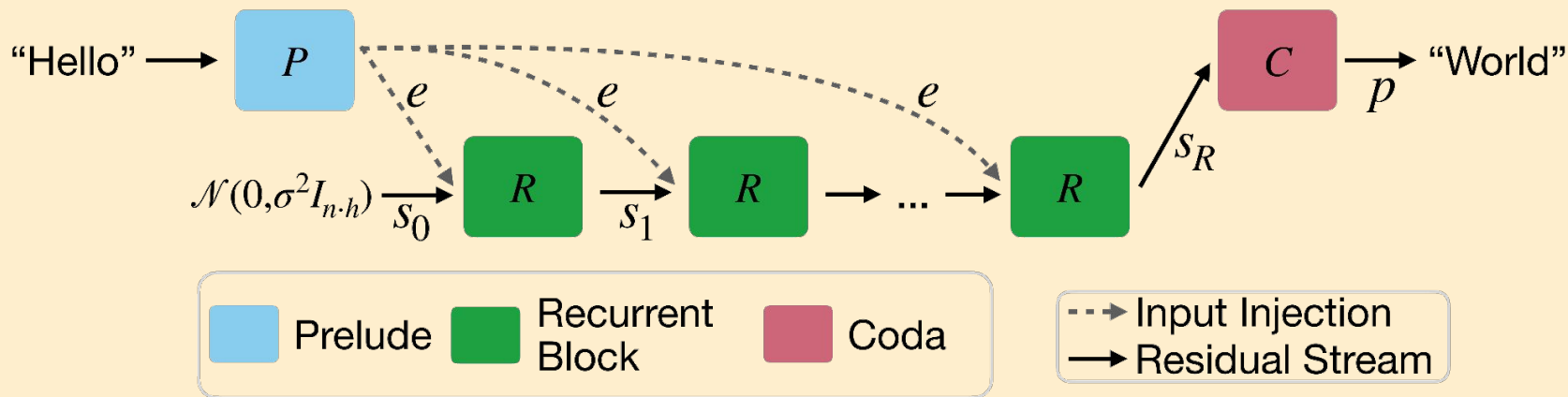
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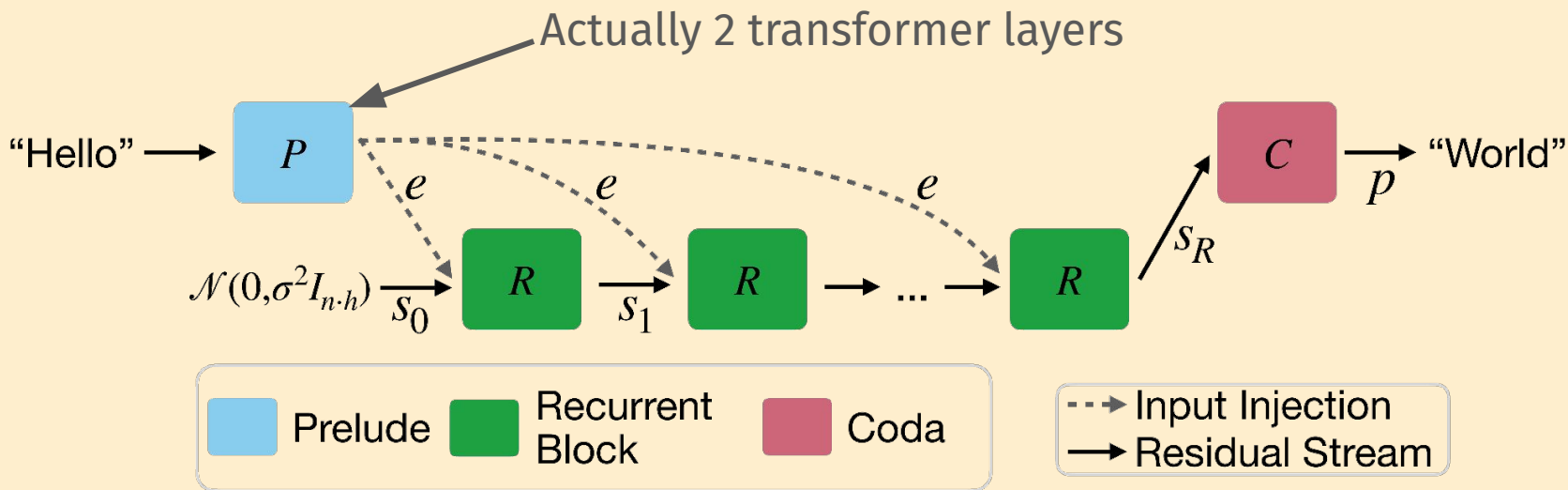
**A scalable recurrent (depth) architecture**



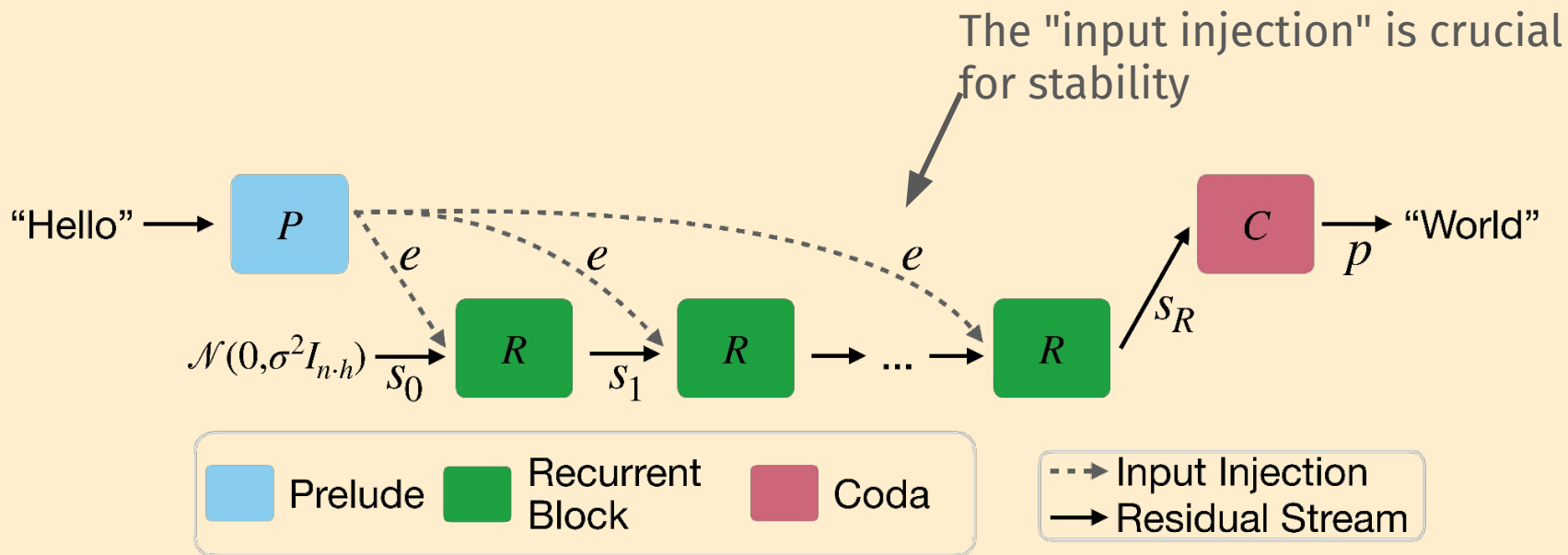
# Why did we call this *latent* recurrent depth?



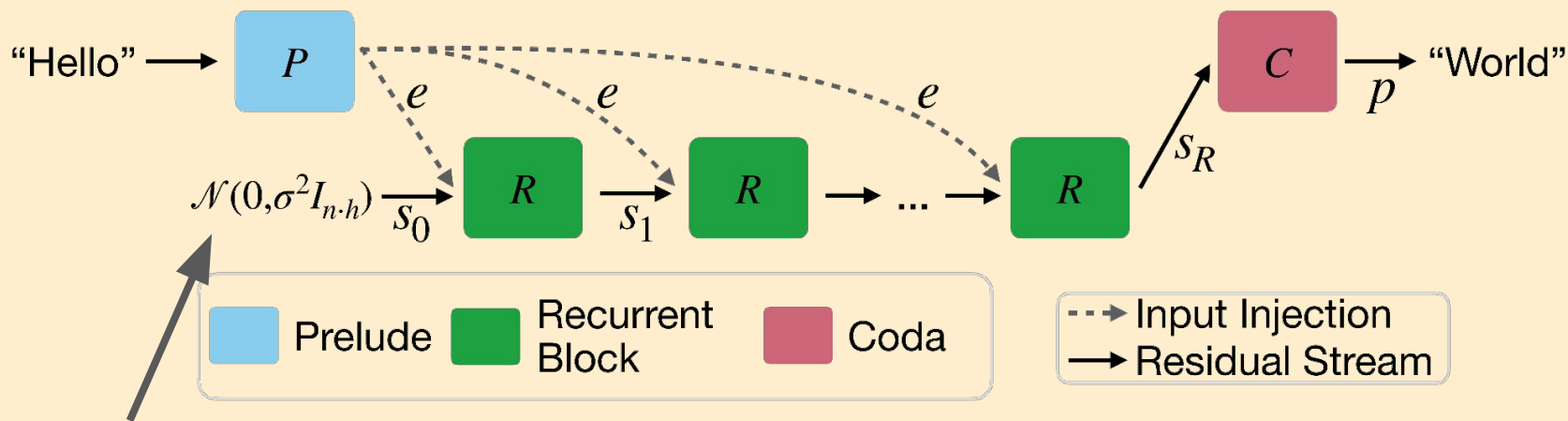
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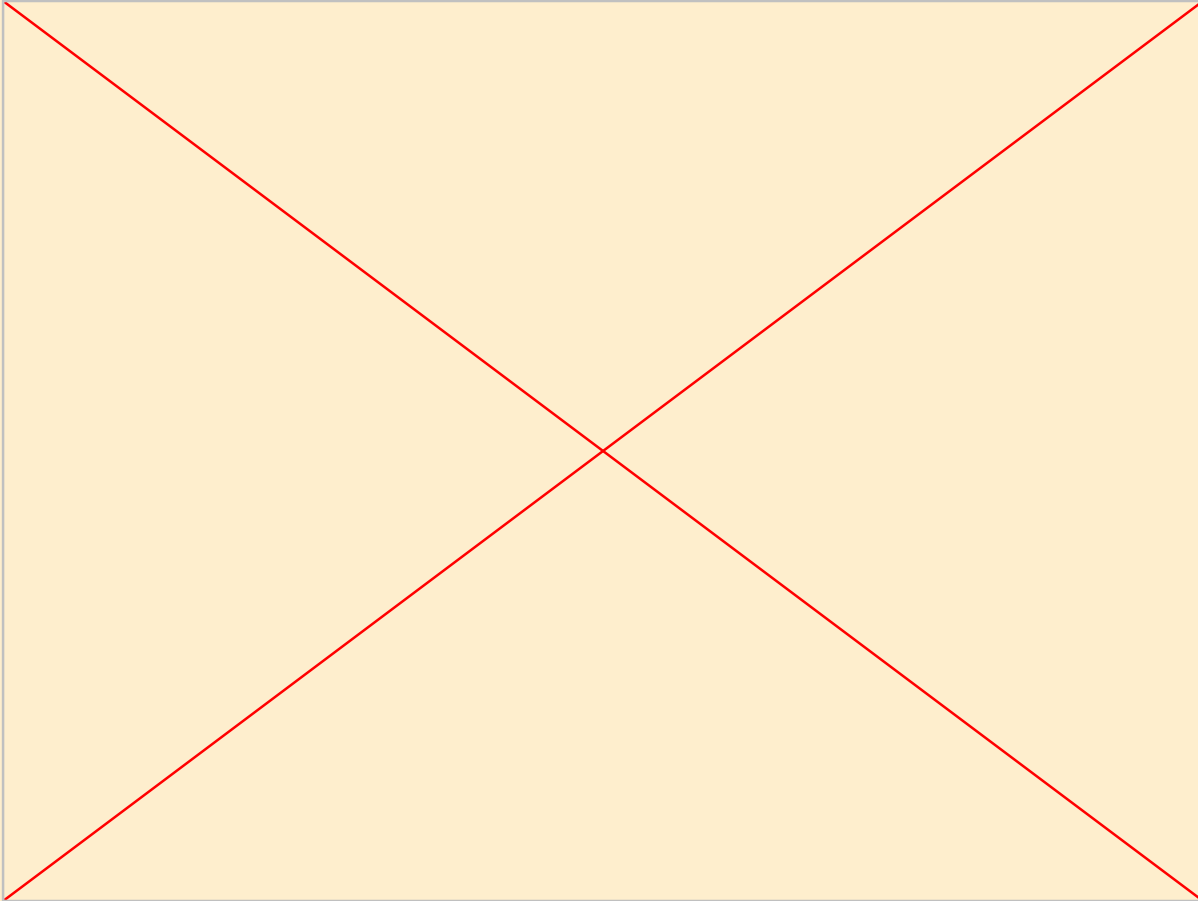


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Diffusion Model connection,  
appears based on findings for  
path independence

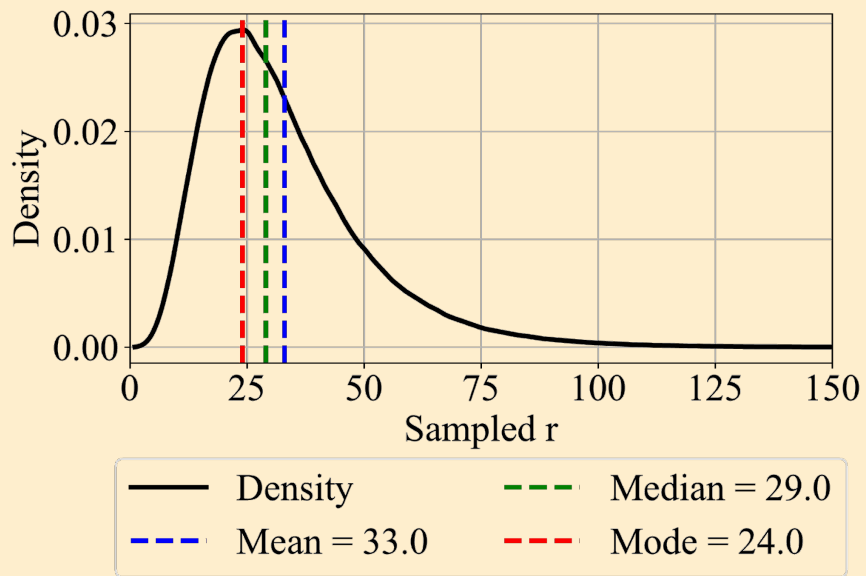
# What does that mean?





# Training Objective

$$\mathcal{L}(\theta) = \mathbb{E}_{\mathbf{x} \in X} \mathbb{E}_{r \sim \Lambda} L(m_{\theta}(\mathbf{x}, r), \mathbf{x}')$$



For every training sequence

- Sample a random\* number of steps  $r$  to recur
- Compute  $r$  forward steps
- Compute loss based on the last  $k$  steps.

# Training Objective Alternatives?

- **Universal Transformers:** Train with halting module
- **Equilibrium Models:** Iterate to convergence, differentiate fixed point based on IFT
- **Weight-shared models:** Just fix number of steps, train as normal
- **Diffusion Model:** Train to denoise target hidden states

# Actually Training a Model at Scale



# How do we show that this *actually* scales?

- 100m parameter, 10B tokens prototypes all work great...

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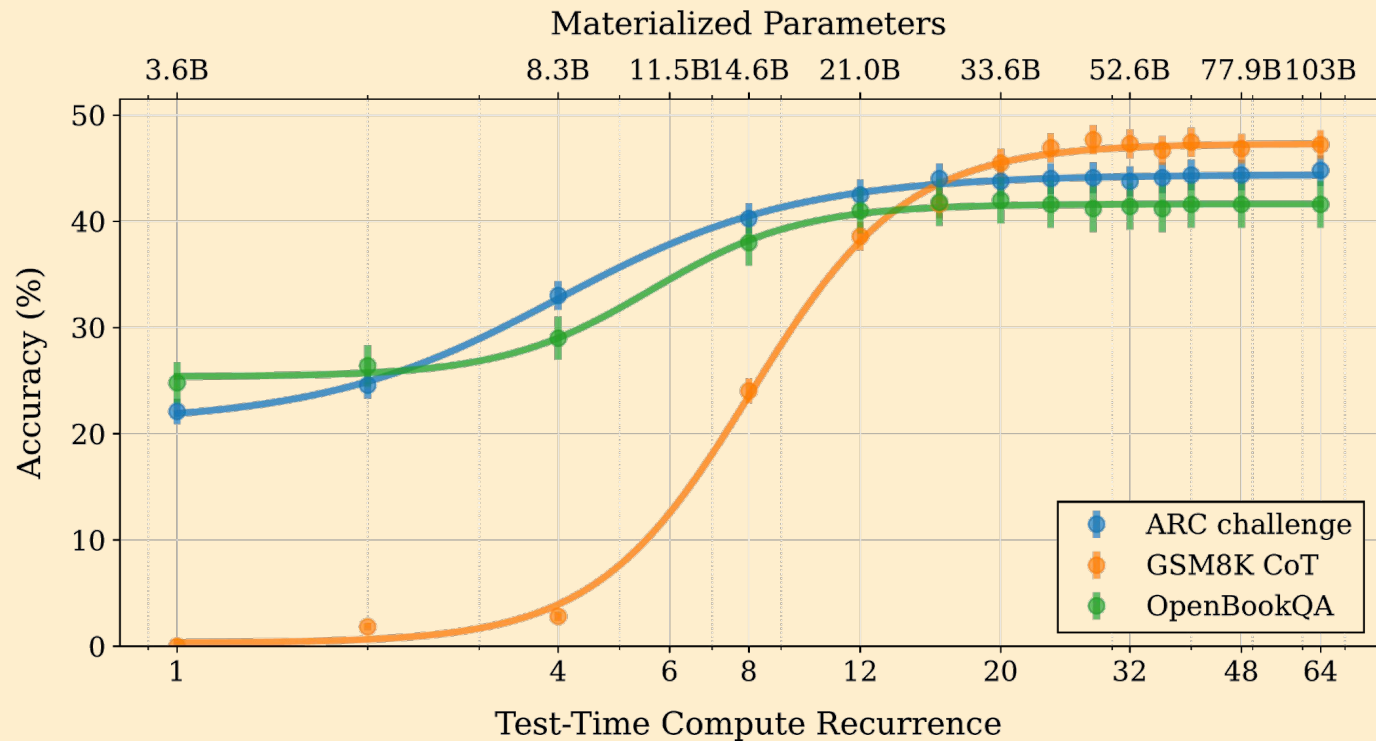
- 2 + 4 + 2 layers, tied embeds, 3.5B parameters
- We target 1T tokens of a wide pretraining mix
- Will it actually train to be a (semi)-competitive language and reasoning model?
- Who will give us compute ...



# Results



## Scaling up Test-Time Compute with Recurrent Depth





# Standard benchmarks

Model	Param	Tokens	ARC-E	ARC-C	HellaSwag	MMLU	OBQA	PiQA	SciQ	WinoGrande
random			25.0	25.0	25.0	25.0	25.0	50.0	25.0	50.0
Amber	7B	1.2T	65.70	37.20	72.54	26.77	41.00	78.73	88.50	63.22
Pythia-2.8b	2.8B	0.3T	58.00	32.51	59.17	25.05	35.40	73.29	83.60	57.85
Pythia-6.9b	6.9B	0.3T	60.48	34.64	63.32	25.74	37.20	75.79	82.90	61.40
Pythia-12b	12B	0.3T	63.22	34.64	66.72	24.01	35.40	75.84	84.40	63.06
OLMo-1B	1B	3T	57.28	30.72	63.00	24.33	36.40	75.24	78.70	59.19
OLMo-7B	7B	2.5T	68.81	40.27	75.52	28.39	42.20	80.03	88.50	67.09
OLMo-7B-0424	7B	2.05T	75.13	45.05	77.24	47.46	41.60	80.09	96.00	68.19
OLMo-7B-0724	7B	2.75T	74.28	43.43	77.76	50.18	41.60	80.69	95.70	67.17
OLMo-2-1124	7B	4T	82.79	57.42	80.50	60.56	46.20	81.18	96.40	74.74
Ours, ( $r = 4$ )	3.5B	0.8T	49.07	27.99	43.46	23.39	28.20	64.96	80.00	55.24
Ours, ( $r = 8$ )	3.5B	0.8T	65.11	35.15	58.54	25.29	35.40	73.45	92.10	55.64
Ours, ( $r = 16$ )	3.5B	0.8T	69.49	37.71	64.67	31.25	37.60	75.79	93.90	57.77
Ours, ( $r = 32$ )	3.5B	0.8T	69.91	38.23	65.21	31.38	38.80	76.22	93.50	59.43

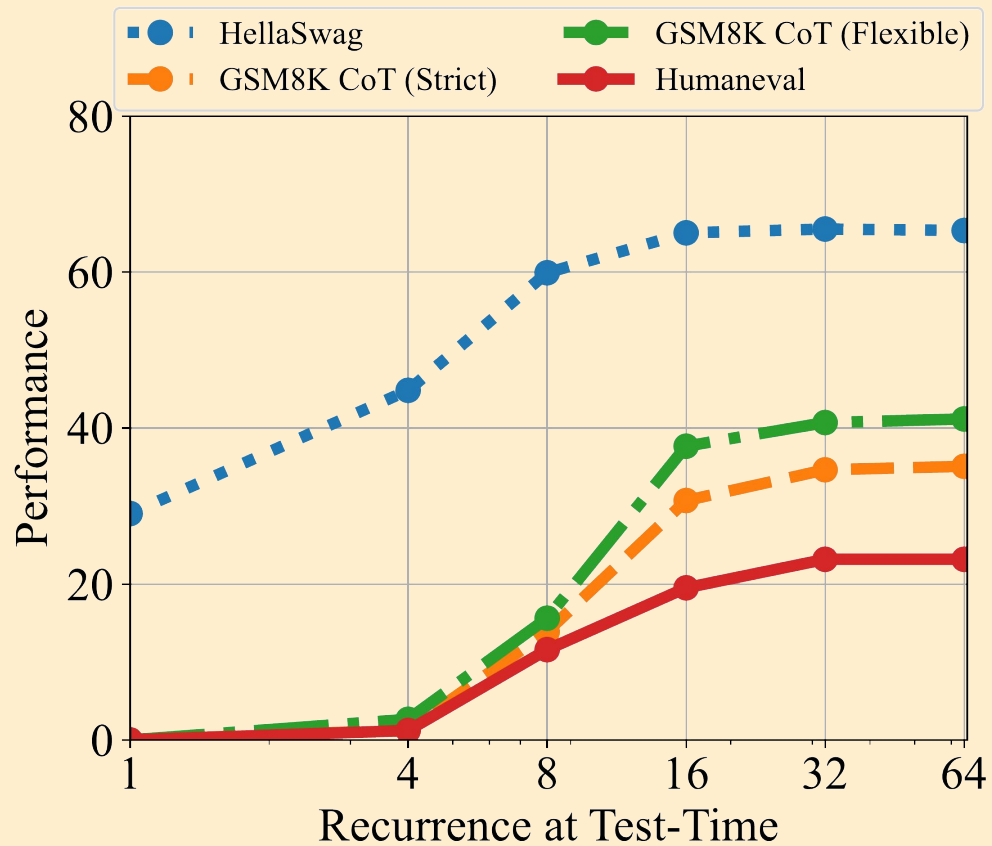
# Reasoning (grade-school math)

Model	GSM8K	GSM8k CoT	Minerva MATH	MathQA
Random	0.00	0.00	0.00	20.00
Amber	3.94/4.32	3.34/5.16	1.94	25.26
Pythia-2.8b	1.59/2.12	1.90/2.81	1.96	24.52
Pythia-6.9b	2.05/2.43	2.81/2.88	1.38	25.96
Pythia-12b	3.49/4.62	3.34/4.62	2.56	25.80
OLMo-1B	1.82/2.27	1.59/2.58	1.60	23.38
OLMo-7B	4.02/4.09	6.07/7.28	2.12	25.26
OLMo-7B-0424	27.07/27.29	26.23/26.23	5.56	28.48
OLMo-7B-0724	28.66/28.73	28.89/28.89	5.62	27.84
OLMo-2-1124-7B	66.72/66.79	61.94/66.19	19.08	37.59
Our w/o sys. prompt ( $r = 32$ )	28.05/28.20	32.60/34.57	12.58	26.60
Our w/ sys. prompt ( $r = 32$ )	24.87/38.13	34.80/42.08	11.24	27.97

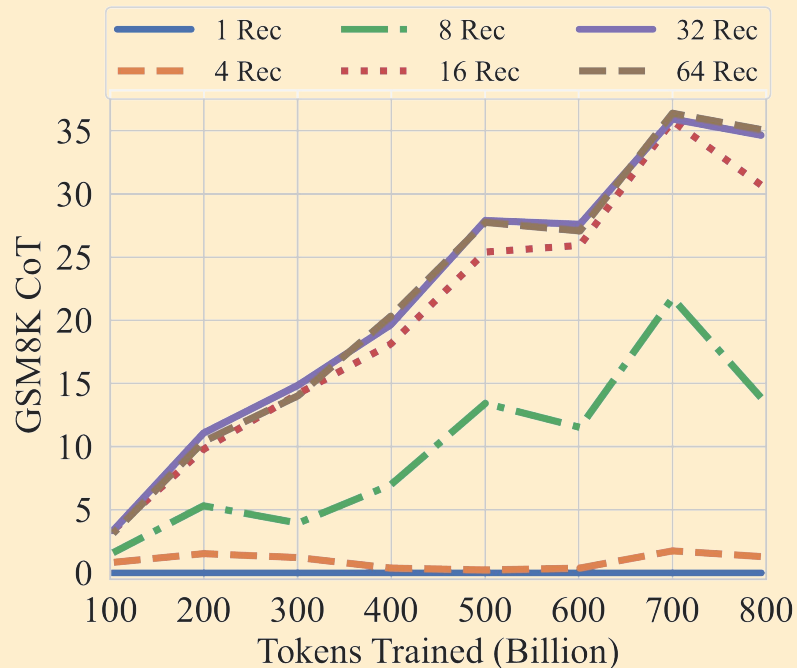
# Reasoning (grade-school math)

Model	Tokens	ARC-E	ARC-C	HellaSwag	MMLU	OBQA	PiQA	SciQ	WinoGrande	GSM8K CoT
Fixed-Depth Baseline	0.18T	46.42	26.96	37.34	24.16	29.60	64.47	73.20	51.78	1.82/2.20
Ours, early ckpt, ( $r = 32$ )	0.18T	53.62	29.18	48.80	25.59	31.40	68.88	80.60	52.88	9.02/10.24
Ours, early ckpt, ( $r = 1$ )	0.18T	34.01	23.72	29.19	23.47	25.60	53.26	54.10	53.75	0.00/0.15
Ours, ( $r = 32$ )	0.8T	69.91	38.23	65.21	31.38	38.80	76.22	93.50	59.43	34.80/42.08
Ours, ( $r = 1$ )	0.8T	34.89	24.06	29.34	23.60	26.80	55.33	47.10	49.41	0.00/0.00

# Scaling Test-Time Compute



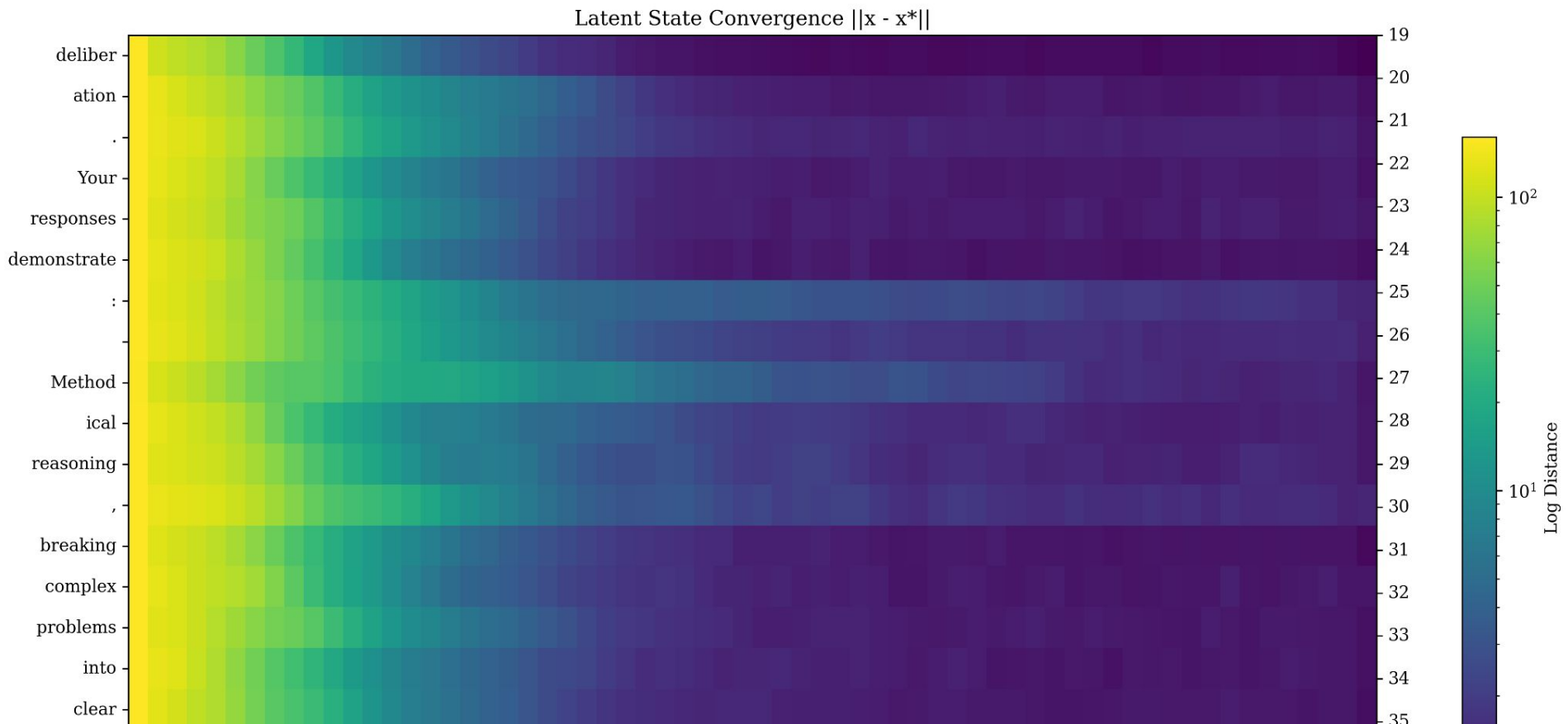
# vs Scaling Pretraining



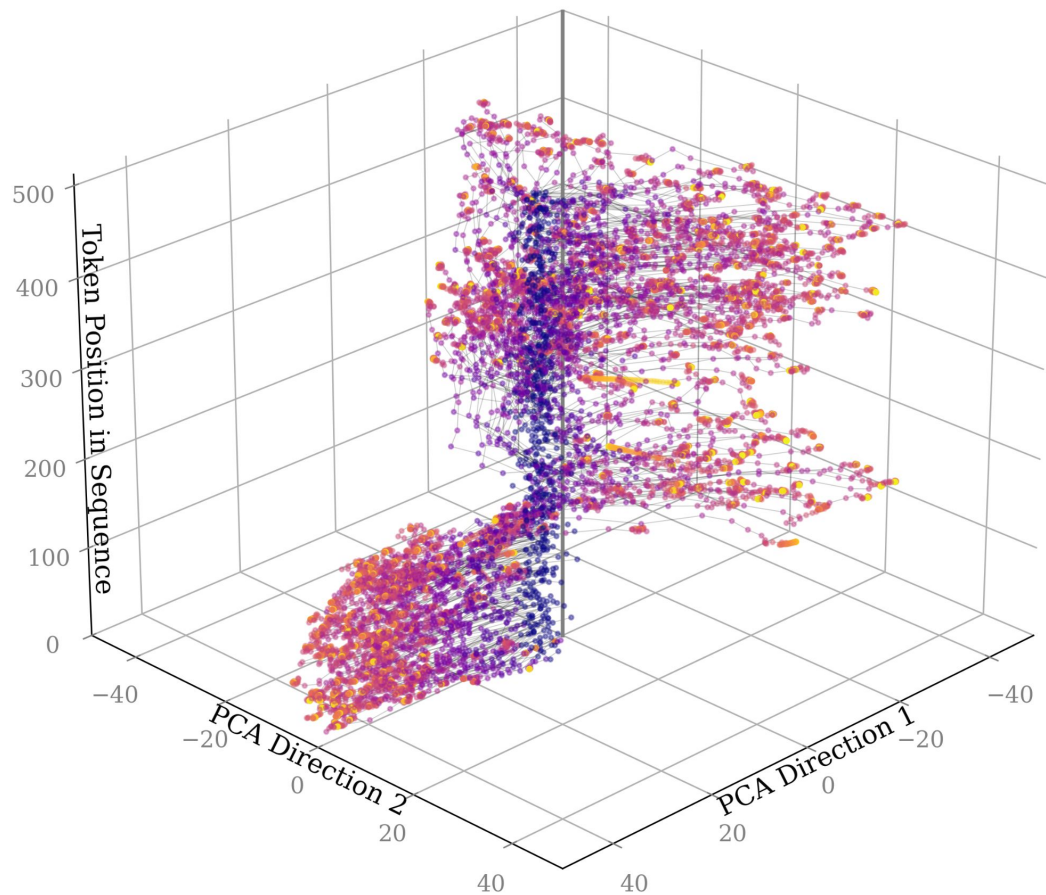
**What is the model doing?**



# Convergence rates per recurrence step at every position

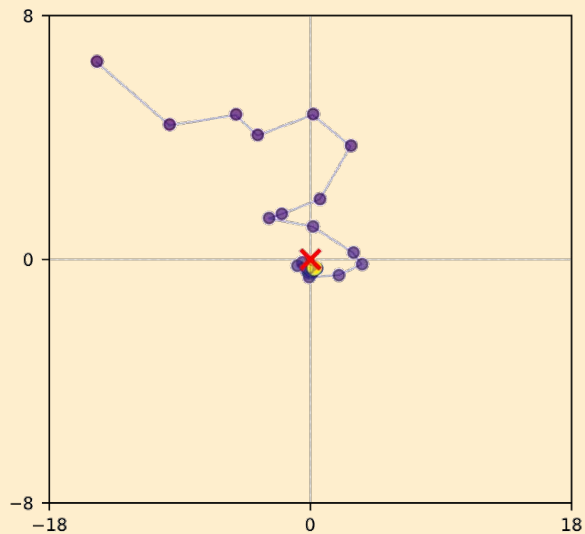


# Token Trajectories

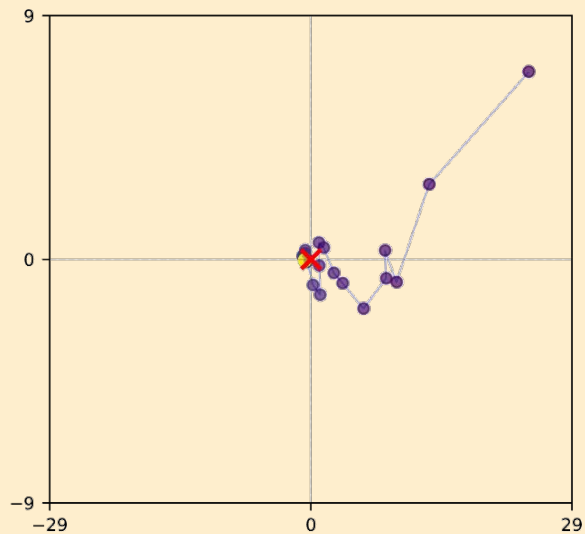


# Emergent Terminal Behaviors

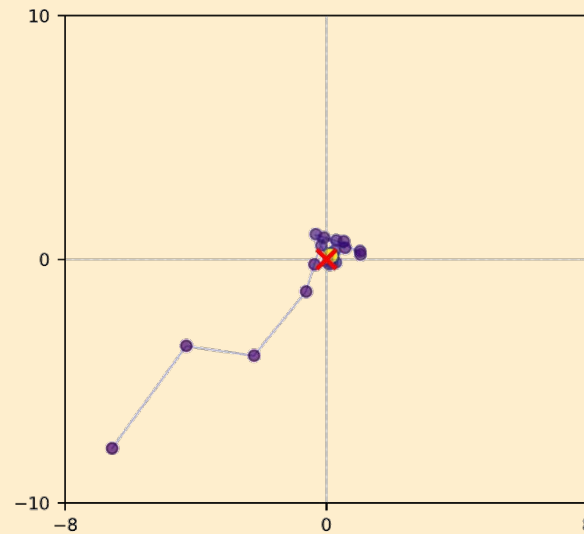
Token: "deeper"  
PC1-PC2



PC3-PC4



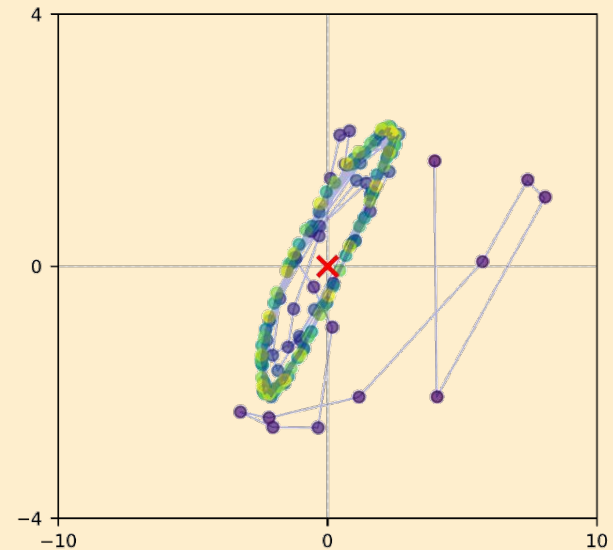
PC5-PC6



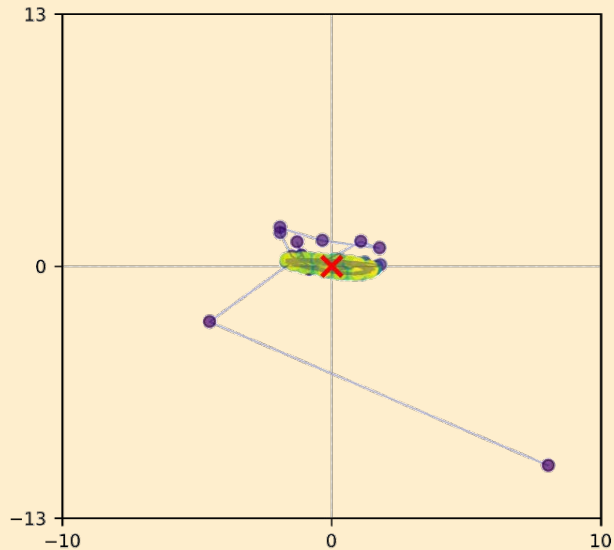


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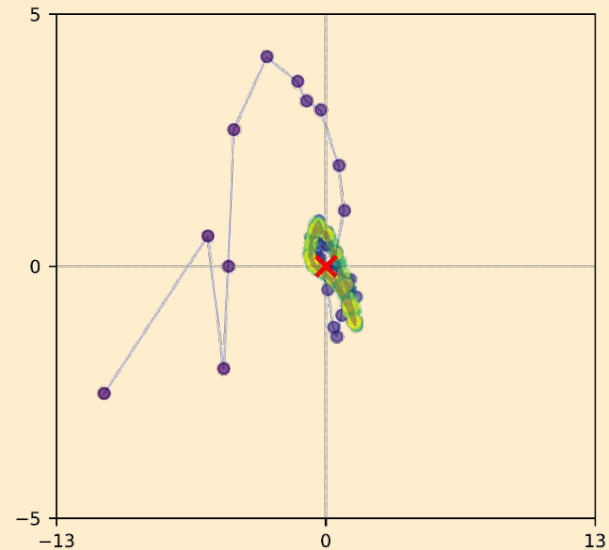
Token: "3"  
PC1-PC2



PC3-PC4

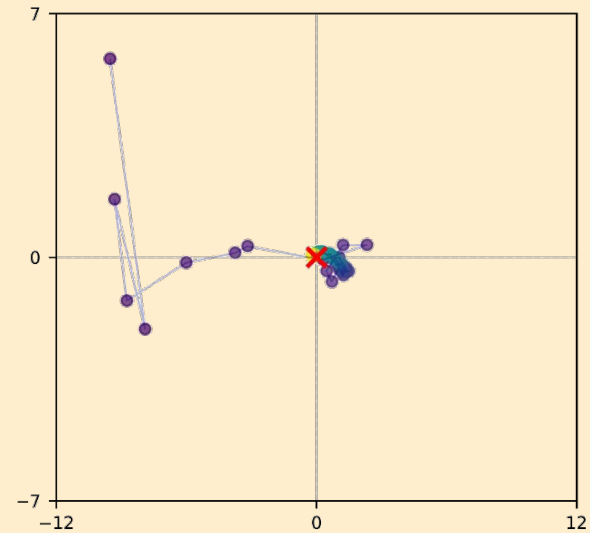


PC5-PC6

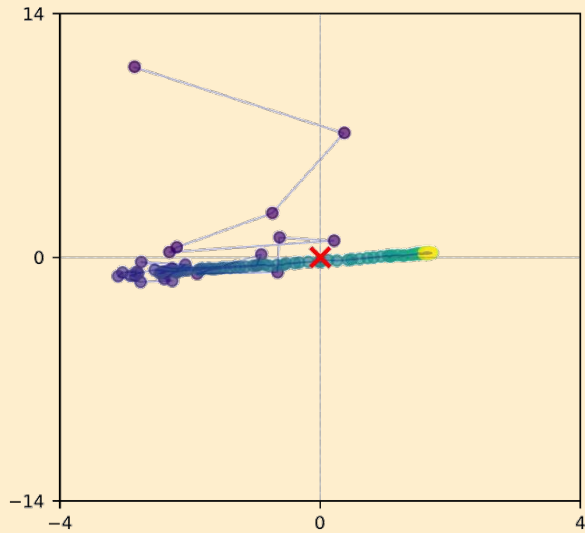


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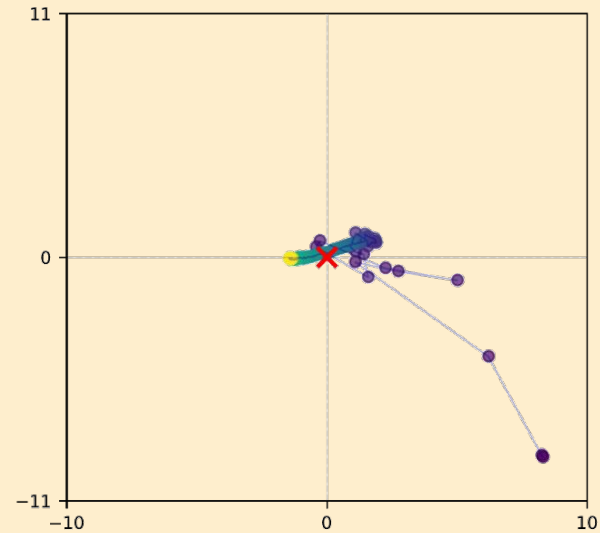
Token: " wrong"  
PC1-PC2



PC3-PC4



PC5-PC6



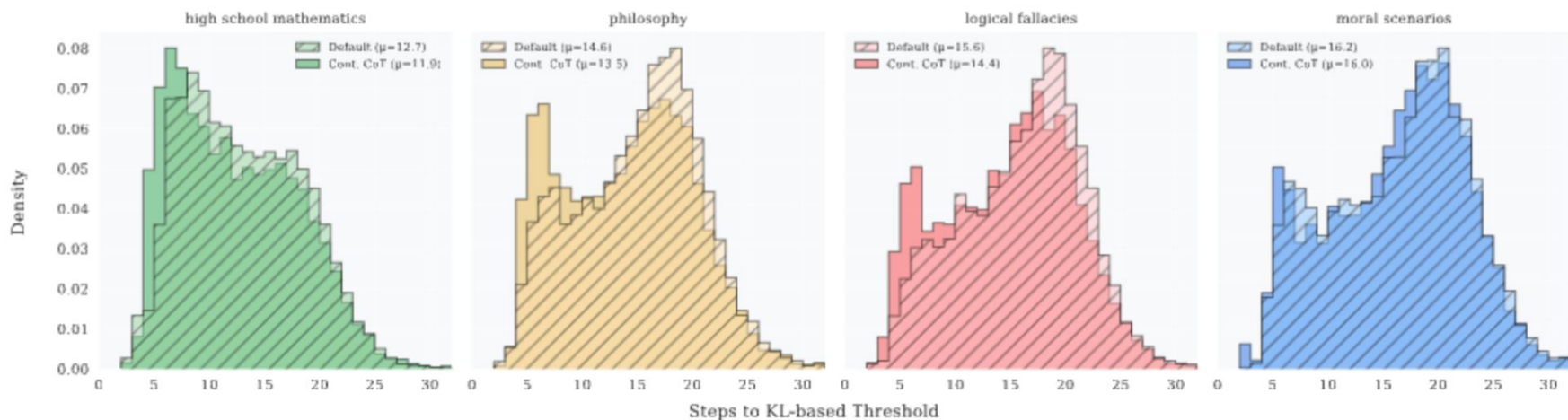
# Takeaways from Trajectories

- Complexity emerges from pretraining
- Different terminal behaviors emerge from simple training objectives
- Harder to analyze model behavior -> requires representation analysis

# Other Advantages of Recurrence



# The model is able to exit *per-token* without training



# Recurrent Depth actually simplifies LLMs

- Simplified speculative decoding
- Zero-shot per-token adaptive computation
- Simplified KV-cache sharing
- Simplified continuous chain of thought



**Conclusions, Takeaways, the Future**

# Conclusions, Takeaways, the Future

- Different paradigm to pre-train models that scales surprisingly far
- How do we get arbitrary extrapolation in compute?
- How to post-train?
- Is this a complementary path to scaling model performance? What is an apples-to-apples comparison to CoT?





**Questions**